

Footprint Size Of A Helicopter-Borne Electromagnetic Induction Sounding System Versus Antenna Altitude By Austin Kovacs

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Helicopter- borne measurements of sea ice

digitally operated frequency-domain electromagnetic-induction (EM) system, electromagnetic-induction (EM) sounding footprint/altitude ratio for helicopter

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Tos-2005 int. ocean research conference polar

Ice Thickness observations with helicopter-borne sensors Footprint of EM ice thickness sensors - pixel size at 100m:

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Sea-ice thickness measurement: recent experiments

Recent Experiments using Helicopter-borne EM-Induction Sensors . the footprint size is reduced, used to identify sea-ice types and other features in SAR

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Strong spatial variability of snow accumulation

Strong spatial variability of snow accumulation observed with helicopter-borne GPR footprint size in the large footprint of helicopter-borne GPR has

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Accurate detection of tree apexes in coniferous

Table 1 Specifications of the helicopter-borne scanning LIDAR system.1,14 Footprint size (cm) 20 30 30

Footprint interval (cm) Flight direction:

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Augc 2004 - ml-struct-svm - multi-label structure svm

Because the wavelength of blue light is roughly the size of an Swedish Ionosonde System ARL UT Ionosonde (Austin, of sound up to 86 kilometers altitude.

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Measuring freshwater-layer plume depths beneath

Measuring freshwater-layer plume depths beneath the land-fast ice of the Mackenzie Delta with Helicopter-borne and floe size distribution along the helicopter

Crrel report 93-12, footprint size of a helicopter

u P M 0 r na ^ 0 Footprint Size of a Helicopter-Borne Electromagnetic Induction Sounding System Versus Antenna Altitude Austin Kovacs, J. Scott Holladay and Clyde J

A helicopter- borne eight-channel ranging

JANUARY 1993 161 A Helicopter-Borne Eight-Channel Ranging Scatterometer for Remote Sensing: the antenna footprint on the HELICOPTER-BORNE RANGING

Comparison of coincident snow-freeboard and sea

from helicopter-borne laser altimetry and electromagnetic size of a helicopter-borne electromagnetic induction sounding system versus antenna

An airborne electromagnetic system on a fixed wing

Therefore the footprint size is not sensitive to the Footprint size of a helicopter-borne electromagnetic induction sounding system versus antenna altitude.

Answers.com - official site

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Automatic detection and classification of

Automatic detection and classification of induction anomalies in helicopter-borne electromagnetic data sets enlarged about the size of two footprints (here 200m)

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A helicopter-borne laser was tested in a coastal Scots pine stand where mean height was Optimal laser footprint size was found to change across data

Article details - a review of helicopter- borne

A review of helicopter-borne electromagnetic methods for groundwater exploration. Authors: As the footprint of AEM systems is rather small,

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The effects of footprint size and sampling density

the effects of footprint size and sampling density in airborne laser scanning to extract individual trees in mountainous terrain y. hirata shikoku research center

Measuring the thicknesses of the freshwater-layer

The footprint size of the EM sensor depends on the height of the sensor above the seawater (Kovacs et al., 1995)
The helicopter-borne electromagnetic

Mapping sea ice thickness with radarsat and a

Electromagnetic-Induction System Footprint Size of a Helicopter-Borne Electromagnetic Induction Sounding System versus Antenna Altitude

Holladay, j. scott 1955- (john scott) [worldcat

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The penetration rate of laser pulses transmitted

(2003) The capability of helicopter-borne laser scanner altimetry and expected tree size distribution from a small-footprint airborne LiDAR:

Observing regional-scale pack-ice decay processes

The footprint size of the HEM sensor Map of the Arctic Ocean and the region (red box) where ice-property data were collected with helicopter-borne sensors during

Estimation of tree heights and stand volume using

A helicopter-borne laser was tested The use of an airborne lidar system for estimating tree heights and stand volume was Optimal laser footprint size was

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3-d remote sensing of woody canopy height and

helicopter-borne scanning laser altimetry and expected tree size WA (1999) Use of large-footprint scanning airborne lidar to estimate

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Pack ice thickness and concentration measurements

Helicopter-borne sensors collected ice system collected video images to document the changes in ice concentration and floe size footprint will take into

Citeseerx comparing ice chart parameters against

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